Package 'h3o'

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compact_cells

Compact H3 Cells

Description

Reduce a set of H3 indices of the same resolution to the minimum number of H3 indices of varying resolution that entirely covers the input area.

Usage

```
compact_cells(x)
uncompact_cells(x, resolution)
```

Arguments

x a vector of H3 indexes.

resolution a scalar integer representing the grid resolution in the range [0, 15].

Value

An H3 vector.

```
x <- h3_from_strings("841f91dffffffff")
y <- uncompact_cells(x, 5)[[1]]
z <- compact_cells(y)
all.equal(x, z)</pre>
```

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get_parents

Hierarchical H3 Grid Functions

Description

Functions used to traverse the hierarchy of H3 grids.

Usage

```
get_parents(x, resolution)
get_children(x, resolution)
get_children_count(x, resolution)
get_children_center(x, resolution)
get_children_position(x, resolution)
get_children_at(x, position, resolution)
```

Arguments

x an H3 vector.

resolution a scalar integer representing the grid resolution in the range [0, 15].

position the integer position in the ordered set of cells.

Details

- get_parents(): returns the parent cells for an H3 vector at a given resolution. Errors if the resolution is smaller than the provided cell.
- get_children(): returns a list of H3 vectors containing the children of each H3 cell at a specified resolution. If the resolution is greater than the cell's resolution an empty vector is returned.
- get_children_count(): returns an integer vector containing the number of children for each cell at the specified resolution.
- get_children_center(): returns the middle child (center child) for all children of an H3 cell at a specified resolution as an H3 vector.
- get_children_position(): returns the position of the observed H3 cell in an ordered list of all children as a child of a higher resolution cell (PR for clearer language welcome).
- get_children_at(): returns the child of each H3 cell at a specified resolution based on its position in an ordered list (PR for clearer language welcome).

Value

See details.

grid_disk

Examples

```
h3_strs <- c("841f91dffffffff", "841fb59ffffffff")
h3 <- h3_from_strings(h3_strs)

get_parents(h3, 3)
get_children(h3, 5)
get_children_count(h3, 6)
get_children_position(h3, 3)
get_children_at(h3, 999, 10)</pre>
```

grid_disk

Grid Traversal

Description

Functions used to traverse the H3 grid.

Usage

```
grid_disk(x, k = 1, safe = TRUE)
grid_ring(x, k = 1)
grid_distances(x, k = 1)
grid_path_cells(x, y)
grid_path_cells_size(x, y)
grid_distance(x, y)
grid_local_ij(x, y)
```

Arguments

X	an H3 vector.
k	the order of ring neighbors. 0 is the focal location (the observed H3 index). 1 is the immediate neighbors of the H3 index. 2 is the neighbors of the 1st order neighbors and so on.
safe	default TRUE. If FALSE uses the fast algorithm which can fail.
у	an H3 vector.

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Details

• grid_disk(): returns the disk of cells for the identified K ring. It is a disk because it returns all cells to create a complete geometry without any holes. See grid_ring() if you do not want inclusive neighbors.

- grid_ring(): returns a K ring of neighbors around the H3 cell.
- grid_distances(): returns a list of numeric vectors indicating the network distances between neighbors in a K ring. The first element is always 0 as the travel distance to one's self is 0. If the H3 index is missing a 0 length vector will be returned.
- grid_path_cells(): returns a list of H3 vectors indicating the cells traversed to get from x to y. If either x or y are missing, an empty vector is returned.
- grid_path_cells_size(): returns an integer vector with the cell path distance between pairwise elements of x and y. If either x or y are missing the result is NA. grid_distance(): returns an integer vector with the network distance between pairwise elements of x and y. If either x or y are missing the result is NA. Effectively grid_path_cells_size() 1.
- grid_local_ij() returns a two column data frame containing the columns i and j which correspond to the i,j coordinate directions to the destination cell.

Value

See details.

Examples

```
h3_strs <- c("841f91dffffffff", "841fb59ffffffff")
h3 <- h3_from_strings(h3_strs)

grid_disk(h3, 1)
grid_ring(h3, 2)
grid_distances(h3, 2)
grid_path_cells(h3, rev(h3))
grid_path_cells_size(h3, rev(h3))
grid_distance(h3, rev(h3))
grid_local_ij(h3, rev(h3))</pre>
```

h3_edges

H3 Edges

Description

Functions to create or work with H3Edge vectors. See Details for further details.

h3_edges

Usage

```
h3_edges(x, flat = FALSE)
h3_shared_edge_sparse(x, y)
h3_shared_edge_pairwise(x, y)
is_edge(x)
is_valid_edge(x)
h3_edges_from_strings(x)
flatten_edges(x)
h3_edge_cells(x)
h3_edge_origin(x)
h3_edge_destination(x)
## S3 method for class 'H3Edge'
as.character(x, ...)
```

Arguments

x an H3 vector

flat default FALSE. If TRUE return a single vector combining all edges of all H3 cells.

y an H3 vector

unused.

Details

- h3_edges(): returns a list of H3Edge vectors for each H3 index. When flat = TRUE, returns a single H3Edge vector.
- h3_shared_edge_pairwise(): returns an H3Edge vector of shared edges. If there is no shared edge NA is returned.
- h3_shared_edge_sparse(): returns a list of H3Edge vectors. Each element iterates through each element of y checking for a shared edge.
- is_edge(): returns TRUE if the element inherits the H3Edge class.
- is_valid_edge(): checks each element of a character vector to determine if it is a valid edge ID.
- h3_edges_from_strings(): create an H3Edge vector from a character vector.
- flatten_edges(): flattens a list of H3Edge vectors into a single H3Edge vector.
- h3_edge_cells(): returns a list of length 2 named H3Edge vectors of origin and destination cells

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- h3_edge_origin(): returns a vector of H3Edge origin cells
- h3_edge_destination(): returns a vector of H3Edge destination cells

Value

See details.

```
# create an H3 cell
x <- h3_from_xy(-122, 38, 5)
# find all edges and flatten
edges <- h3_edges(x) |>
  flatten_edges()
# check if they are all edges
is_edge(edges)
# check if valid edge strings
is_valid_edge(c("115e22da7fffffff", "abcd"))
# get the origin cell of the edge
h3_edge_origin(edges)
# get the destination of the edge
h3_edge_destination(edges)
# get both origin and destination cells
h3_edge_cells(edges)
# create edges from strings
h3_edges_from_strings(c("115e22da7fffffff", "abcd"))
# create a vector of cells
cells_ids <-c(
  "85e22da7fffffff", "85e35ad3fffffff",
  "85e22dafffffff", "85e35adbfffffff",
  "85e22da3fffffff"
)
cells <- h3o::h3_from_strings(cells_ids)</pre>
# find shared edges between the two pairwise
h3_shared_edge_pairwise(cells, rev(cells))
# get the sparse shared eddge. Finds all possible shared edges.
h3_shared_edge_sparse(cells, cells)
```

h3_from_xy

Description

Create H3 indices from sfc objects, vectors of x and y coordinates, or H3 string IDs.

Usage

```
h3_from_xy(x, y, resolution)
h3_from_points(x, resolution)
h3_from_strings(x)
h3_to_points(x)
h3_to_vertexes(x)
## S3 method for class 'H3'
as.character(x, ...)
flatten_h3(x)
is_h3(x)
```

Arguments

Details

- h3_from_points(): takes an sfc_POINT object and creates a vector of H3 cells
- h3_from_strings(): converts a character vector of cell indexes to an H3 vector
- h3_from_xy(): converts vectors of x and y coordinates to an H3 vector
- h3_to_points(): converts an H3 vector to a either an sfc_POINT object or a list of sfg POINT objects.
- h3_to_vertexes(): converts an H3 vector to an sfc_MULTIPOINT object or a list of MULTIPOINT objects.

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Value

See details.

Examples

```
h3_from_xy(-90, 120, 5)
h3_from_strings("85f29383fffffff")
if (requireNamespace("sf")) {
  # create random points
  pnts <- sf::st_cast(</pre>
    sf::st_sfc(
      sf::st_multipoint(matrix(runif(10, max = 90), ncol = 2)),
      crs = 4326
    "POINT"
  )
  # convert to H3 objects
  h3s <- h3_from_points(pnts, 5)
  h3_to_vertexes(h3s)
 h3_to_points(h3s)
}
h3\_ids \leftarrow c("831f91ffffffff", "831fb5fffffffff", "831f94ffffffff")
flatten_h3(
 list(
    NULL,
    h3_from_strings(h3_ids),
    h3_from_strings(h3_ids[1])
  )
)
```

h3_resolution

H3 Inspection Functions

Description

Functions that provide metadata about H3 indexes.

Usage

```
h3_resolution(x)
h3_base_cell(x)
```

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```
is_valid_h3(x)
is_res_class_iii(x)
is_pentagon(x)
get_face_count(x)
```

Arguments

Χ

an H3 vector.

Details

- h3_resolution(): returns the resolution of each H3 cell.
- h3_base_cell(): returns the base cell integer.
- is_valid_h3(): given a vector of H3 index string IDs, determine if they are valid.
- is_res_class_iii(): determines if an H3 cell has Class III orientation.
- is_pentagon(): determines if an H3 cell is one of the rare few pentagons.
- get_face_count(): returns the number of faces that intersect with the H3 index.

Value

See details.

```
cells_ids <-c(
    "85e22da7ffffffff", "85e35ad3ffffffff",
    "85e22dafffffffff", "85e35adbffffffff",
    "85e22db7ffffffff", "85e35e6bffffffff",
    "85e22da3fffffff"
)

cells <- h3o::h3_from_strings(cells_ids)

h3_resolution(cells)
h3_base_cell(cells)
is_valid_h3(c("85e22db7ffffffff", NA, "oopsies"))
is_res_class_iii(cells)
is_res_class_iii(h3_from_xy(0, 0, 10))
is_pentagon(h3_from_strings("08FD60000000000"))
get_face_count(cells)</pre>
```

is_nb_pairwise 11

is_nb_pairwise

H3 index neighbors

Description

Test if two H3 cells are neighbors.

Usage

```
is_nb_pairwise(x, y)
is_nb_sparse(x, y)
```

Arguments

```
x an H3 vector.
y and H3 vector.
```

Value

is_nb_pairwise() returns a logical vector wheraas is_nb_sparse() returns a list with logical vector elements.

Examples

```
cells_ids <-c(
    "85e22da7fffffff", "85e35ad3fffffff",
    "85e22daffffffff", "85e35adbffffffff",
    "85e22db7ffffffff", "85e35e6bffffffff",
    "85e22da3fffffff"
)
cells <- h3o::h3_from_strings(cells_ids)
is_nb_pairwise(cells, rev(cells))
is_nb_sparse(cells, cells)</pre>
```

sfc_to_cells

Convert sf geometry to H3 Cells

Description

Given a vector of sf geometries (class sfc) create a list of H3 vectors. Each list element contains the vector of H3 cells that cover the geometry.

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Usage

```
sfc_to_cells(x, resolution, containment = "intersect")
```

Arguments

for h3_from_points() an object of class sfc_POINT. For h3_from_strings() a character vector of H3 index IDs. For h3_from_xy() a numeric vector of longitudes.

resolution an integer indicating the H3 cell resolution. Must be between 0 and 15 inclusive.

default "intersect". Must be one of "intersect", "centroid", or "boundary".

See details.

Details

Note, use flatten_h3() to reduce the list to a single vector.

The Containment Mode determines if an H3 cell should be returned.

- "centroid" returns every cell whose centroid are contained inside of a polygon. This is the fastest option but may not cover the entire polygon.
- "boundary" this returns the cells which are completely contained by the polygon. Much of a polygon might not be covered using this approach.
- "intersect" ensures that a polygon is entirely covered. If an H3 cell comes in contact with the polygon it will be returned. This is the default.
- "contains" behaves the same as "intersect", but also handles the case where the geometry is being covered by a cell without intersecting with its boundaries. In such cases, the covering cell is returned.

Value

An H3 vector.

```
if (interactive() && rlang::is_installed("sf")) {
  nc <- sf::st_read(system.file("shape/nc.shp", package = "sf"), quiet = TRUE)
  geo <- sf::st_geometry(nc)
  cells <- sfc_to_cells(geo, 5)

  head(cells)

  plot(flatten_h3(cells))
}</pre>
```

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