

Advanced case study options

GMSE: an R package for generalised management strategy evaluation (Supporting Information 4)

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Fine-tuning simulation conditions using `gmse_apply`

Here we demonstrate how simulations in GMSE can be more fine-tuned to specific empirical situations through the use of `gmse_apply`. To do this, we use the same scenario described in [SI3](#); we first recreate the basic scenario run in `gmse` using `gmse_apply`, and then build in additional modelling details including (1) [custom placement of user land](#), (2) [parameterisation of individual user budgets](#), and (3) [density-dependent movement of resources](#). We emphasise that these simulations are provided only to demonstrate the use of GMSE, and specifically to show the flexibility of the `gmse_apply` function, not to accurately recreate the dynamics of a specific system or make management recommendations.

We reconsider the case of a protected waterfowl population that exploits agricultural land (e.g., [Fox and Madsen, 2017](#); [Mason et al., 2017](#); [Tulloch et al., 2017](#); [Cusack et al., 2018](#)). The manager attempts to keep the waterfowl at a target abundance, while users (farmers) attempt to maximise agricultural yield on the land that they own. We again parameterise our model using demographic information from the Taiga Bean Goose (*Anser fabalis fabalis*), as reported by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#). Relevant parameter values are listed in the table below.

Table 1: GMSE simulation parameter values inspired by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#)

Parameter	Value	Description
<code>remove_pr</code>	0.122	Goose density-independent mortality probability
<code>lambda</code>	0.275	Expected offspring production per time step
<code>res_death_K</code>	93870	Goose carrying capacity (on adult mortality)
<code>RESOURCE_ini</code>	35000	Initial goose abundance
<code>manage_target</code>	70000	Manager’s target goose abundance
<code>res_death_type</code>	3	Mortality (density and density-independent sources)

Additionally, we continue to use the following values for consistency, except in the case of `stakeholders`, where we reduce the number of farmers to `stakeholders = 8`. This is done to for two reasons. First, it speeds up simulations for the purpose of demonstration; second, it makes the presentation of our custom landscape ownership easier to visualise (see below).

Table 2: Non-default GMSE parameter values chosen by authors

Parameter	Value	Description
<code>manager_budget</code>	10000	Manager’s budget for setting policy options
<code>user_budget</code>	10000	Users’ budgets for actions
<code>public_land</code>	0.4	Proportion of the landscape that is public

Parameter	Value	Description
stakeholders	8	Number of stakeholders
land_ownership	TRUE	Users own landscape cells
res_consume	0.02	Landscape cell output consumed by a resource
observe_type	3	Observation model type (survey)
agent_view	1	Cells managers can see when conducting a survey

All other values are set to GMSE defaults, except where specifically noted otherwise.

Re-creating gmse simulations using gmse_apply

We now recreate the simulations in [SI3](#), which were run using the `gmse` function, in `gmse_apply`. Doing so requires us to first initialise simulations using one call of `gmse_apply`, then loop through multiple time steps that again call `gmse_apply`; results of interest are recorded in a data frame (`sim_sum_1`). Following the protocol introduced in [SI2](#), we can call the initialising simulation `sim_old`, and use the code below to read in the relevant parameter values.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 100000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200);
```

Note that the argument `get_res = "Full"` causes `sim_old` to retain all of the relevant data structures for simulating a new time step and recording simulation results. This includes the key simulation output, which is located in `sim_old$basic_output`, which is printed below.

```
## $resource_results
## [1] 34268
##
## $observation_results
## [1] 34268
##
## $manager_results
##      resource_type scaring culling castration feeding help_offspring
## policy_1          1      NA     517          NA      NA          NA
##
## $user_results
##      resource_type scaring culling castration feeding help_offspring
## Manager          1      NA      0          NA      NA          NA
## user_1            1      NA    187          NA      NA          NA
## user_2            1      NA    189          NA      NA          NA
## user_3            1      NA    187          NA      NA          NA
## user_4            1      NA    188          NA      NA          NA
## user_5            1      NA    187          NA      NA          NA
## user_6            1      NA    187          NA      NA          NA
## user_7            1      NA    188          NA      NA          NA
## user_8            1      NA    188          NA      NA          NA
##      tend_crops kill_crops
```

```
## Manager      NA      NA
## user_1       NA      NA
## user_2       NA      NA
## user_3       NA      NA
## user_4       NA      NA
## user_5       NA      NA
## user_6       NA      NA
## user_7       NA      NA
## user_8       NA      NA
```

We can then loop over 30 time steps to recreate the simulations from [SI3](#). In these simulations, we are specifically interested in the resource and observation outputs, as well as the manager policy and user actions for culling, which we record below in the data frame `sim_sum_1`. The inclusion of the argument `old_list` tells `gmse_apply` to use parameters and values from the list `sim_old` in the new time step.

```
sim_sum_1 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_1[time_step, 1] <- time_step;
  sim_sum_1[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_1[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_1[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_1[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_1) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
                        "Cull_count");
print(sim_sum_1);
```

```
##      Time Pop_size Pop_est Cull_cost Cull_count
## [1,]  1    32508   32508     798      983
## [2,]  2    32113   32113     933      842
## [3,]  3    32342   32342     982      801
## [4,]  4    33199   33199    1003      785
## [5,]  5    37150   37150    1002      785
## [6,]  6    38243   38243     994      792
## [7,]  7    39644   39644    1002      785
## [8,]  8    41276   41276     997      787
## [9,]  9    43198   43198    1009      778
## [10,] 10   45557   45557    1001      785
## [11,] 11   47920   47920    1001      785
## [12,] 12   50212   50212     982      801
## [13,] 13   52988   52988     997      786
## [14,] 14   55701   55701    1000      786
## [15,] 15   58673   58673    1002      785
## [16,] 16   61784   61784     996      788
## [17,] 17   65225   65225     983      801
## [18,] 18   68843   68843    1010      778
## [19,] 19   72816   72816      10     29122
## [20,] 20   46687   46687    1009      778
## [21,] 21   48928   48928     996      787
## [22,] 22   51222   51222     997      786
## [23,] 23   53715   53715    1003      785
## [24,] 24   56523   56523     992      793
## [25,] 25   59436   59436    1010      778
```

```
## [26,] 26 62808 62808 1002 785
## [27,] 27 66315 66315 1003 785
## [28,] 28 70070 70070 10 29182
## [29,] 29 43585 43585 1008 778
## [30,] 30 45709 45709 997 788
```

The above output from `sim_sum_1` shows the data frame that holds the information we were interested in pulling out of our simulation results. All of this information was available under the list element `sim_new$basic_output`, but other list elements of `sim_new` might also be useful to record. It is important to remember that this example of `gmse_apply` is using the default resource, observation, manager, and user sub-models. Custom sub-models could produce different outputs in `sim_new` (see [SI2](#) for examples). For default sub-models, there are some list elements that might be especially useful. These elements can potentially be edited *within the above loop* to dynamically adjust simulations. For more explanation of built-in GMSE data arrays, see [SI7](#).

- `sim_new$resource_array`: A table holding all information on resources. Rows correspond to discrete resources, and columns correspond to resource properties: (1) ID, (2-4) types (not currently in use), (5) x-location, (6) y-location, (7) movement parameter, (8) time, (9) density independent mortality parameter (`remove_pr`), (10) reproduction parameter (`lambda`), (11) offspring number, (12) age, (13-14) observation columns, (15) consumption rate (`res_consume`), and (16-20) recorded experiences of user actions (e.g., was the resource culled or scared?).
- `sim_new$AGENTS`: A table holding basic information on agents (manager and users). Rows correspond to a unique agent, and columns correspond to agent properties: (1) ID, (2) type (0 for the manager, 1 for users), (3-4) additional type options not currently in use, (5-6), x and y locations (usually ignored), (7) movement parameter (usually ignored), (8) time, (9) agent's viewing ability in cells (`agent_view`), (10) error parameter, (11-12) values for holding marks and tallies of resources, (13-15) values for holding observations, (16) yield from landscape cells, (17) budget (`manager_budget` and `user_budget`).
- `sim_new$observation_vector`: Estimate of total resource number from the observation model (`observation_array` also holds this information in a different way depending on `observe_type`)
- `sim_new$LAND`: The landscape on which interactions occur, which is stored as a 3D array with `land_dim_1` rows, `land_dim_2` columns, and 3 layers. Layer 1 (`sim_new$LAND[,1]`) is not currently used in default sub-models, but could be used to store values that affect resources and agents. Layer 2 (`sim_new$LAND[,2]`) stores crop yield from a cell, and layer 3 (`sim_new$LAND[,3]`) stores the owner of the cell (value corresponds to the agent's ID).
- `sim_new$manage_vector`: The cost of each action as set by the manager. For even more fine-tuning, individual costs for the actions of each agent can be set for each user in `sim_new$manager_array`.
- `sim_new$user_vector`: The total number of actions performed by each user. A more detailed breakdown of actions by individual users is held in `sim_new$user_array`.

Next, we show how to adjust the landscape to manually set land ownership in `gmse_apply`.

1. Custom placement of user land

By default, all farmers in GMSE are allocated the same number of landscape cells, which are simply placed in order of the farmer's ID. Public land is produced by placing landscape cells that are technically owned by the manager, and therefore have landscape cell values of 1. The image below shows this landscape for the eight farmers from `sim_old`.

```
image(x = sim_old$LAND[,3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```

We can change the ownership of cells by manipulating `sim_old$LAND[,3]`. First we initialise a new `sim_old` below.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_d4eath_K = 93870, RESOURCE_ini = 35000,
```

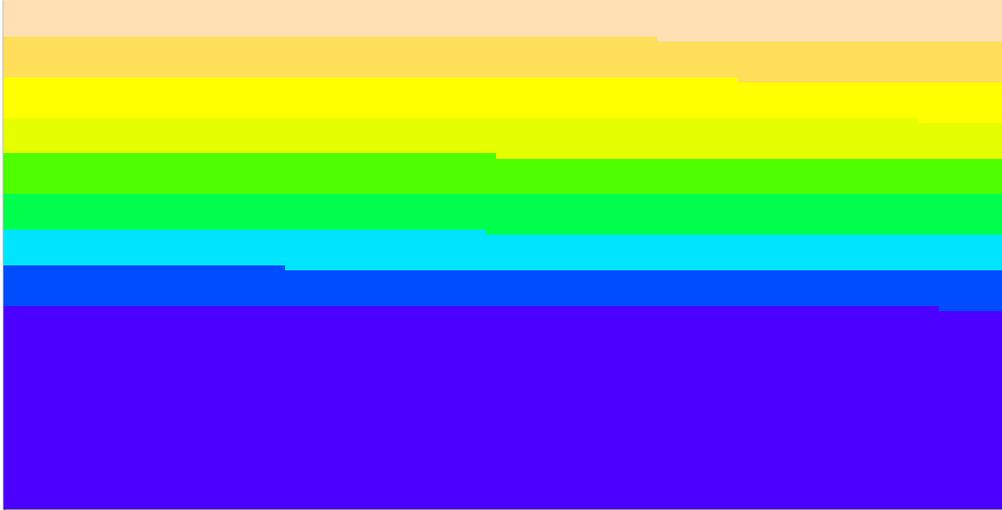


Figure 1: Default position of land ownership by farmers.

```

manage_target = 70000, res_death_type = 3,
manager_budget = 10000, user_budget = 10000,
public_land = 0.4, stakeholders = 8, res_consume = 0.02,
res_birth_K = 200000, land_ownership = TRUE,
observe_type = 3, agent_view = 1, converge_crit = 0.01,
ga_mingen = 200);

```

Because we have not specified landscape dimensions in the above, the landscape reverts to the default size of 100 by 100 cells. We can then manually assign landscape cells to the eight farmers, whose IDs range from 2-9 (ID value 1 is the manager). Below we do this to make eight different sized farms.

```

sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1; # Public land
image(x = sim_old$LAND[, ,3], col = topo.colors(9), xaxt = "n", yaxt = "n");

```

The above image shows the modified landscape stored in `sim_old`, which can now be incorporated into simulations using `gmse_apply`. We can think of all the plots on the left side of the landscape as farms of various sizes, while the blue area of the landscape on the right is public land.

2. Parameterisation of individual user budgets

Perhaps we want to assume that farmers have different budgets, which are correlated in some way to the number of landscape cells that they own. Custom user budgets can be set by manipulating `sim_old$AGENTS`, the last column of which (column 17) holds the budget for each user. Agent IDs (as stored on the landscape above) correspond to rows of `sim_old$AGENTS`, so individual budgets can be directly input as desired. We can do this manually (e.g., `sim_old$AGENTS[2, 17] <- 4000`), or, alternatively, if farmer budget positively

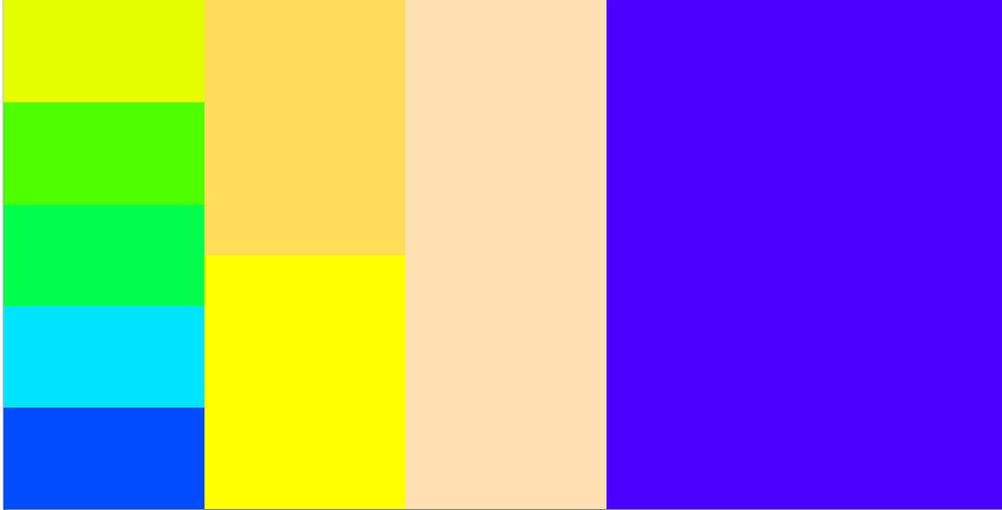


Figure 2: Land ownership by farmers as customised in gmse_apply.

correlates to landscape owned, we can use a loop to input values as below.

```
for(ID in 2:9){
  cells_owned      <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}
```

The number of cells owned by the manager (1) and each farmer (2-8) is therefore listed in the table below.

ID	1	2	3	4	5	6	7	8	9
Budget	10000	4000	4000	4000	4000	4000	10000	10000	20000

As with `sim_old$LAND` values, changes to `sim_old$AGENTS` will be retained in simulations looped through `gmse_apply`.

3. Density-dependent movement of resources

Lastly, we consider a more nuanced change to simulations, in which the rules for movement of resources are modified to account for density-dependence. Assume that geese tend to avoid aggregating, such that if a goose is located on the same cell as too many other geese, then it will move at the start of a time step. Programming this movement rule can be accomplished by creating a new function to apply to the resource data array `sim_old$resource_array`. Below, a custom function is defined that causes a goose to move up to 5 cells in any direction if it finds itself on a cell with more than 10 other geese. As with default GMSE simulations, movement is based on a torus landscape (where no landscape edge exists, so that if resources move off of one side of the landscape they appear on the opposite side).

```
avoid_aggregation <- function(goose_table, land_dim_1 = 100, land_dim_2 = 100){
  goose_number <- dim(goose_table)[1] # How many geese are there?
  for(goose in 1:goose_number){ # Loop through all rows of geese
    x_loc <- goose_table[goose, 5];
    y_loc <- goose_table[goose, 6];
    shared <- sum(goose_table[,5] == x_loc & goose_table[,6] == y_loc);
    if(shared > 10){
      new_x <- x_loc + sample(x = -5:5, size = 1);
      new_y <- y_loc + sample(x = -5:5, size = 1);
      if(new_x < 0){ # The 'if' statements below apply the torus
        new_x <- land_dim_1 + new_x; 6
      }
      if(new_x >= land_dim_1){
        new_x <- new_x - land_dim_1;
      }
    }
  }
}
```

With the above function written, we can apply the new movement rule along with our [custom farm placement](#) and [custom farmer budgets](#) to the simulation of goose population dynamics.

Simulation with custom farms, budgets, and goose movement

Below shows an example of `gmse_apply` with custom landscapes, farmer budgets, and density-dependent goose movement rules.

```
# First initialise a simulation
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 10000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200, res_move_type = 0);

# By setting `res_move_type = 0`, no resource movement will occur in gmse_apply
# Adjust the landscape ownership below
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1;

# Change the budgets of each farmer based on the land they own
for(ID in 2:9){
  cells_owned <- sum(sim_old$LAND[, ,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}

# Begin simulating time steps for the system
sim_sum_2 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  # Apply the new movement rules at the beginning of the loop
  sim_old$resource_array <- avoid_aggregation(sim_old$resource_array);
  # Next, move on to simulate (old_list remembers that res_move_type = 0)
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_2[time_step, 1] <- time_step;
  sim_sum_2[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_2[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_2[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_2[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_2) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
  "Cull_count");
print(sim_sum_2);
```

```
##      Time Pop_size Pop_est Cull_cost Cull_count
## [1,]    1   34048   34048     788         74
```

## [2,]	2	34626	34626	894	64
## [3,]	3	35876	35876	946	60
## [4,]	4	37798	37798	975	60
## [5,]	5	43761	43761	978	60
## [6,]	6	46067	46067	1008	52
## [7,]	7	48857	48857	998	56
## [8,]	8	51977	51977	977	60
## [9,]	9	55408	55408	985	60
## [10,]	10	59308	59308	977	60
## [11,]	11	63553	63553	970	60
## [12,]	12	67542	67542	994	58
## [13,]	13	71721	71721	468	124
## [14,]	14	76276	76276	385	151
## [15,]	15	81302	81302	394	150
## [16,]	16	86630	86630	428	137
## [17,]	17	92550	92550	428	137
## [18,]	18	98760	98760	438	132
## [19,]	19	101621	101621	412	140
## [20,]	20	102475	102475	424	136
## [21,]	21	102668	102668	431	134
## [22,]	22	103216	103216	425	137
## [23,]	23	103612	103612	428	137
## [24,]	24	103845	103845	424	137
## [25,]	25	103600	103600	431	136
## [26,]	26	103651	103651	437	132
## [27,]	27	103323	103323	422	137
## [28,]	28	103267	103267	429	136
## [29,]	29	103196	103196	432	136
## [30,]	30	103239	103239	417	138

Conclusions

In this example, we showed how the built-in resource, observation, manager, and user sub-models can be customised by manipulating the data within the data structures that they use. The goal was to show how software users can work with these existing sub-models and data structures to customise GMSE simulations. Readers seeking even greater flexibility (e.g., replacing an entire built-in sub-model with a custom sub-model) should refer to [SI2](#) that introduces `gmse_apply` more generally. Future versions of GMSE are likely to expand on the built-in options available for simulation; requests for such expansions, or contributions, can be submitted to [GitHub](#).

References

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